NEMA 4, Proportional, Spring Return, 24 V, for Use with Honeywell® Electronic Series 90 or a 0 to 135 Ω Input

- Torque min. 180 in-lb
- Control fixed, 0 to 135 Ω input, or Honeywell series 90 (fixed)
- Feedback 2 to 10 VDC (DEFAULT)



For proportional modulation of dampers and control valves in HVAC systems. The AFB24-MFT95 N4, AFX24-MFT95 N4 provides mechanical spring return operation for reliable fail-safe application.

Default/Configuration

Default parameters for 0 to 135 Ω Input applications of the AFB24-MFT95 N4 and AFX24-MFT95 N4 actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. However the control input cannot be modified via MFT PC tool software. The parameters noted in the Technical Data table are variable.

These parameters can be changed by three means:

- Pre-set configurations from Belimo
- Custom configurations from Belimo
- Configurations set by the customer using the MFT PC tool (version 3.4 or higher) software application.

Operation

The AFB24-MFT95 N4, AFX24-MFT95 N4 actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position.

The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches.

The AFB24-MFT95 N4, AFX24-MFT95 N4 is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption.

Dimensions (inches [mr Clamp Configurations Ø 1/2" Field Selectable	3/4" Centered 1 (Default) (F	.05" Centered ield Selectable)	D312_config
0.79'[20]	A A 6.45°(163.9)	0.39°[10]	_
3.62°(92.1)	9.37"[238]	1.12*(28.5)	









Technical Data		AFB24-MFT95 N4, AFX24-MFT95 N4		
Power supply		24 VAC, +/- 20%, 50/60 Hz		
		24 VDC, +20% / -10%		
Power	running	7.5 W		
consumption♦	holding	3 W		
Transformer sizing♦		10 VA (Class 2 power source)		
Electrical connection				
AFB24-MFT95 N4		3 ft, 18 GA plenum cable,		
		with 1/2" conduit connector		
AFX24-MFT95 N4		3 ft [1m], 18 GA plenum cable,		
		with 1/2" conduit connector		
Overload protection		electronic throughout 0 to 95° rotation		
Operating range Y		0 to 135 Ω Honeywell Electronic Series 90,		
		0 to 135 Ω input		
Feedback output U*		2 to 10 VDC, 0.5 mA max		
Torque		minimum 180 in-lb (20 Nm)		
Direction	spring	reversible with cw/ccw mounting inside housing		
of rotation*	motor	reversible with built-in switch		
Mechanical		95° (adjustable with mechanical end stop, 35° to 95°)		
angle of rotation*				
Running time	spring	<20 seconds @ -4°F to 122°F [-20° C to 50° C];		
		<60 seconds @ -22°F [-30° C]		
	motor*	150 seconds (default), variable (70 to 220 seconds)		
Angle of Rotation		off (default)		
adaptation				
Position indication		visual indicator, 0° to 95°		
		(0° is spring return position)		
Manual override		5 mm hex crank (¾16" Allen), supplied		
Humidity		max. 95% RH non-condensing		
Ambient temperature		-22 to 122° F (-30 to 50° C)		
Storage temperature		-40 to 176° F (-40 to 80° C)		
Housing		UL Type 4, NEMA 4, IP66		
Housing material		polycarbonate		
Noise level		≤40dB(A) motor @ 150 seconds, run time dependent		
		≤62dB(A) spring return		
Agency listings †		cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-		
		1:02, CE acc. to 2004/108/EC & 2006/95/EC		
Quality standard		ISO 9001		
Servicing		maintenance free		
Weight		9.7 lbs. (4.4 kg)		

^{*} Variable when configured with MFT options

† Rated Impulse Voltage 800V, Type of action 1.AA (1.AA.B for -S version), Control Pollution Degree 4.

800-543-9038 USA 866-805-7089 CANADA 203-791-8396 LATIN AMERICA

Programmed for 70 seconds motor run time. At 150 sec motor run time, transformer sizing is 8.5 VA and power consumption is 6 W running / 3 W holding.

AFB24-MFT95 N4, AFX24-MFT95 N4

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Proportional Potentiometric Control - Wiring Diagrams

X INSTALLATION NOTES

Actuators with plenum rated cable do not have numbers on wires; use color codes instead. Actuators with appliance cables are numbered.

Provide overload protection and disconnect as required.

Actuators and controller must have separate transformers.

Consult controller instruction data for more detailed information.

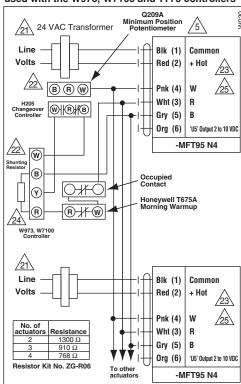
Resistor value depends on the type of controller and the number of actuators. No resistor is used for one actuator. Honeywell® resistor kits may also be

To reverse control rotation, use the reversing switch.

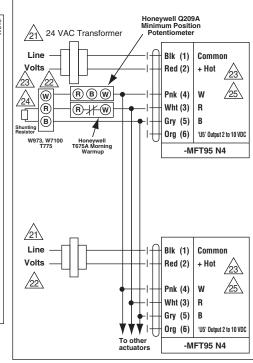
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

WARNING Live Electrical Components!

Typical wiring diagrams for multiple actuators used with the W973, W7100 and T775 controllers

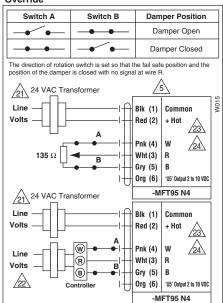


Used with the W973 and W7100 controllers

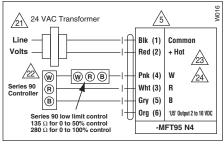


Wire Colors 3 = White 1 = Black5 = Gray 2 = Red 4 = Pink6 = Orange

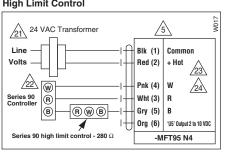
Override



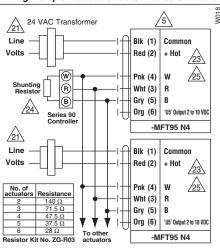
Low Limit Control



High Limit Control



Wiring Multiple Actuators to a Series 90 Controller



Wiring Multiple Actuators to a Series 90 Controller using a Minimum Position Potentiometer

