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Technical Data		EFB24-MFT-S N4, EFX24-MFT-S N4(H)
Power supply		24 VAC, +/- 20%, 50/60 Hz
,		24 VDC, +20% / -10%
Power	running	9.5 W / heater 21 W
consumption♦	holding	
Transformer sizing ♦		16 VA / heater 21 VA
Electrical connection		terminal block(s) inside junction box with knockouts
Overload protection		electronic throughout 0 to 95° rotation
Operating range Y*		2 to 10 VDC, 4 to 20 mA (default)
		variable (VDC, PWM, floating point, on/off)
Input impedance		100 kΩ for 2 to 10 VDC (0.1 mA)
•		500 Ω for 4 to 20 mA
		1500 Ω for PWM, floating point and on/off control
Feedback output U*		2 to 10 VDC, 0.5 mA max (default)
Torque		270 in-lb [30 Nm] minimum
Direction of	spring	reversible with cw/ccw mounting
rotation*	motor	reversible with built-in switch
Mechanical		95° (adjustable with mechanical end stop, 35° to 95°)
angle of rotation*		
Running time	spring	<20 sec @ -4°F to 122°F [-20° C to 50° C];
-		<60 sec @ -22°F [-30° C]
	motor*	150 seconds (default), variable (60 to 150 seconds)
spring (w/heater)		< 20 sec @ -22°F to 122°F [-30°C to 50°C];
,		< 60 sec @ -40°F [-40°C]
Angle of rotation		off (default)
adaptation		
Override control*		min position = 0%
		mid. position = 50%
		max. position = 100%
Position indication	1	visual indicator, 0° to 95°
		(0° is spring return position)
Manual override		5 mm hex crank (3/16" Allen), supplied
Humidity		max 95% RH, non-condensing
Ambient temperature		-22 to 122° F (-30 to 50° C)
with heater		-40°F to 122°F [-40°C to 50°C]
Storage temperature		-40 to 176° F (-40 to 80° C)
Housing		NEMA 4, IP66, Enclosure Type4
Housing material		aluminum diecast and plastic casing
Noise level		≤45.3dB(A) motor @ 150 seconds, run time dependent
		≤71.4dB(A) spring return
Agency listings †		cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-
		1:02, CE acc. to 2004/108/EC & 2006/95/EC
Quality standard		ISO 9001
Servicing		maintenance free
Weight		10 lbs [4.54 kg], 10.1 lbs [4.59 kg] with heater

- * Variable when configured with MFT options
- \dagger Rated Impulse Voltage 800V, Type of action 1.AA (1.AA.B for -S version), Control Pollution Degree 4.
- ϕ Programmed for 60 sec motor run time. At 150 sec motor run time, transformer sizing is 12 VA and power consumption is 7 W running / 4.5 W holding.

EFB24-MFT-S N4, EFX24-MFT-S N4(H)

Auxiliary switches 2 x SPDT 3A (0.5A) @ 250 VAC, UL approved one set at 10°, and one set at 85°

- . Torque min. 270 in-lb for control of air dampers
- Control 2 to 10 VDC (Default)
- Feedback 2 to 10 VDC (Default)

Application

For proportional modulation of dampers in HVAC systems. The EFB24-MFT-S N4, EFX24-MFT-S N4(H) provides mechanical spring return operation for reliable fail-safe application.

Default/Configuration

Default parameters for 2 to 10 VDC applications of the EFB24-MFT-S N4, EFX24-MFT-S N4(H) actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters noted in the Technical Data table are variable.

These parameters can be changed by three means:

- · Pre-set or custom configurations from Belimo
- Configurations set by the customer using the MFT PC tool (version 3.4 or higher) software application.
- · Handheld ZTH-GEN

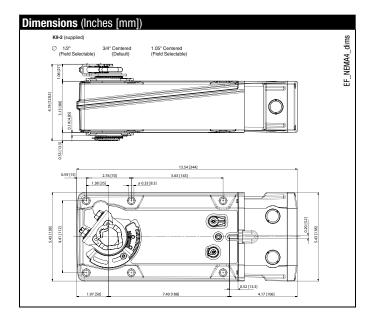
Operation

The EFB24-MFT-S N4, EFX24-MFT-S N4(H) actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position.

The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches.

The EFB24-MFT-S N4, EFX24-MFT-S N4(H) is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The EFB24-MFT-S N4, EFX24-MFT-S N4(H) actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

NOTE: Please see documentation on Multi-Function Technology.





Accessories		
IND-EFB	Damper position indicator	
KH-EFB	Crank arm	
K9-2	Universal clamp for up to 1.05" diameter jackshafts	
Tool-07	13 mm wrench	
ZG-EFB	Crank arm adaptor kit	

NOTE: When using EFB24-MFT-S N4, and EFX24-MFT-S N4(H) actuators, only use accessories

For actuator wiring information and diagrams, refer to Belimo Wiring Guide.

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counterclockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus Approved and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Wiring Diagrams



💢 INSTALLATION NOTES



Provide overload protection and disconnect as required.



CAUTION Equipment Damage!

Actuators may be connected in parallel if not mechanically mounted to the same shaft. Power consumption and input impedance must be observed.



Actuators may also be powered by 24 VDC.



Position feedback cannot be used with Triac sink controller. The actuator internal common reference is not compatible.



Control signal may be pulsed from either the Hot (source) or the Common (sink) 24 VAC line.



Contact closures A & B also can be triacs.



A & B should both be closed for triac source and open for triac sink.



For triac sink the common connection from the actuator must be connected to the hot connection of the controller.



APPLICATION NOTES



Meets UL requirements without the need of an electrical ground



The ZG-R01 500 Ω resistor may be used.



WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

