

| Technical Data | EFB24-SR N4, EFB24-SR-S N4, EFX24-SR-S N4(H) |
| :---: | :---: |
| Power supply | $\begin{aligned} & 24 \text { VAC } \pm 20 \%, 50 / 60 \mathrm{~Hz} \\ & 24 \text { VDC }+20 \% /-10 \% \end{aligned}$ |
| Power consumptionrunning <br> holding | $8 \mathrm{~W} /$ heater 21 W |
|  | 4.5 W |
| Transformer sizing | 14 VA (class 2 power source) / heater 21 VA |
| Electrical connection | terminal block(s) inside junction box with knockouts |
| Overload protection | electronic throughout 0 to $95^{\circ}$ rotation |
| Operating range Y | 2 to $10 \mathrm{VDC}, 4$ to 20mA |
| Input impedance | $100 \mathrm{k} \Omega$ for 2 to $10 \mathrm{VDC}(0.1 \mathrm{~mA})$ $500 \Omega$ for 4 to 20 mA |
| Feedback output U | 2 to 10 VDC (max. 0.5 mA$)$ |
| Torque | 270 in-lb [30 Nm] minimum |
| Direction of rotation spring <br> motor | reversible with CW/CCW mounting |
|  | reversible with built-in switch |
| Mechanical angle of rotation | $95^{\circ}$ (adjustable with mechanical end stop, $35^{\circ}$ to $95^{\circ}$ ) |
| Running time spring | $\begin{aligned} & <20 \text { seconds @ }-4^{\circ} \mathrm{F} \text { to } 122^{\circ} \mathrm{F}\left[-20^{\circ} \mathrm{C} \text { to } 50^{\circ} \mathrm{C}\right] ; \\ & <60 \text { seconds @ }-22^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right] \end{aligned}$ |
|  | 95 seconds |
|  | $\begin{aligned} & <20 \mathrm{sec} @-22^{\circ} \mathrm{F} \text { to } 122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C} \text { to } 50^{\circ} \mathrm{C}\right] ; \\ & <60 \mathrm{sec} @-40^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right] \end{aligned}$ |
| Position indication | visual indicator, $0^{\circ}$ to $95^{\circ}$ ( $0^{\circ}$ is full spring return position) |
| Manual override | 5 mm hex crank ( $3 / 16{ }^{\prime \prime}$ Allen), supplied |
| Humidity | max. 95\% RH non-condensing |
| Ambient temperature with heater | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
|  | $-40^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.80^{\circ} \mathrm{C}\right]$ |
| Housing | NEMA 4, IP66, Enclosure Type4 |
| Housing material | aluminum diecast and plastic casing |
| Agency listings $\dagger$ | cULus acc. to UL60730-1A/-2-14, CAN/CSA E607301:02, CE acc. to 2004/108/EC \& 2006/95/EC |
| Noise level | $\leq 56.5 \mathrm{~dB}(\mathrm{~A})$ motor @ 95 seconds $\leq 71.4 \mathrm{~dB}(\mathrm{~A})$ spring return |
| Servicing | maintenance free |
| Quality standard | IS0 9001 |
| Weight | 10 lbs [ 4.54 kg ], 10.1 lbs [ 4.59 kg ] with heater |
| $\dagger$ Rated Impulse Voltage 800V, Type of action 1.AA (1.AA.B for -S version), Control Pollution Degree 4. |  |
| EFB24-SR-S N4, EFX24-SR-S N4(H) |  |
| Auxiliary switches | 2 x SPDT 3A (0.5A) @ 250 VAC, UL approved one set at $10^{\circ}$, and one set at $85^{\circ}$ |

## Torque min. 270 in -lb, for control of air dampers

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications.
The actuator is mounted directly to a damper shaft up to 1.05 " in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft.
The actuator operates in response to a 2 to 10 VDC, or with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

## Operation

The EFB N4 and EFX N4 series actuators provide true spring return operation for reliable fail-safe application and positive close-off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator.

The EFB N4 and EFX N4 series provide $95^{\circ}$ of rotation and is provided with a graduated position indicator showing $0^{\circ}$ to $95^{\circ}$.

The EFB N4 and EFX N4 series use a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches.
The EFB24-SR-S N4 and EFX24-SR-S N4(H) versions are provided with two built-in auxiliary switches. These SPDT switches provide safety interfacing or signaling, for example, for fan start-up. The switching function at the fail-safe position is fixed at $+10^{\circ}$, the other switch function is fixed at $85^{\circ}$. The EFB24-SR N4, EFB24-SR-S N4, and EFX24-SR-S $\mathrm{N} 4(\mathrm{H})$ actuator is shipped at $+5^{\circ}\left(5^{\circ}\right.$ from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

## Dimensions (Inches [mm])



Accessories

| IND-EFB | Damper position indicator |
| :--- | :--- |
| KH-EFB | Crank arm |
| K9-2 | Universal clamp for up to 1.05" diameter jackshafts |
| Tool-07 | 13 mm wrench |
| ZG-EFB | Crank arm adaptor kit |

NOTE: When using EFB24-SR N4, EFB24-SR-S N4, and EFX24-SR-S N4(H) actuators, only use accessories listed on this page.
For actuator wiring information and diagrams, refer to Belimo Wiring Guide.

## Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05 " diameter. The actuator must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counterclockwise fail-safe operation. Actuators shall use a brushes DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULLs Approved and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

## X' installation notes

1
Provide overload protection and disconnect as required.

## CAUTION Equipment Damage!

Actuators may be connected in parallel.
Power consumption and input impedance must be observed.
Up to 4 actuators may be connected in parallel if not mechanically mounted to the same shaft. With 4 actuators wired to one $500 \Omega$ resistor. Power consumption must be observed.
Actuator may also be powered by 24 VDC .
For end position indication, interlock control, fan startup, etc., EFB24-SR-S N4 and EFX24-SR-S N4 incorporates two built-in auxiliary switches: 2 x SPIT, 3A ( 0.5 A ) @250 VAC, UL Approved, one switch is fixed at $+10^{\circ}$, the other is fixed at $85^{\circ}$.
Only connect common to neg. (-) leg of control circuits

## APPLICATION NOTES

The ZG-R01 $500 \Omega$ resistor converts the 4 to 20 mA control signal to 2 to 10 VC.

## WARNING Live Electrical Components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical componets could result in death or serious injury.


2 to 10 VDC control


## 4 to 20 mA control with 2 to 10 VDC feedback output



## Auxiliary switches



NEMA 4 Heater

